

Arctic sea ice modelling: introducing the Uvic model with the granular sea ice model

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Outline

- Description of the UVic model and the granular model
- Sea ice rheology in the granular sea ice model
- Research objectives
- Preliminary results

The UVic model version 2.6

- global with a resolution of 1.8° (lat) by 3.6° (long)
- oceanic component: MOM 2.2
 - 3D ocean with 19 unequally spaced levels
- the poles can be rotated to avoid the problem of grid convergence
- atmospheric component:
 - EMBM with moisture advection and dynamical feedbacks

Weaver et al. 2001

The granular sea ice model: the dynamics

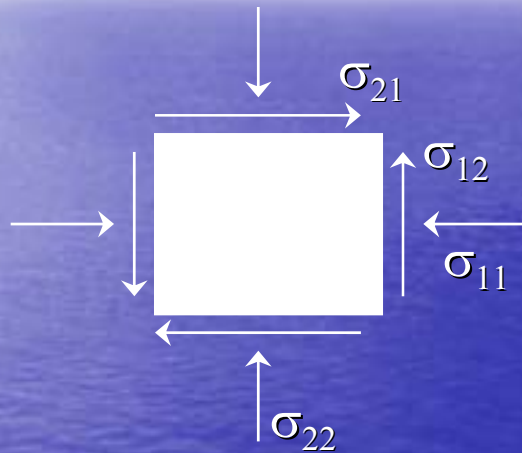
- the major difference with other models is in the parameterization of the rheology term
- sea ice is treated as a slowly deforming granular material
- dilatancy effect included

$$-\rho_i h f (k \times u) + A(\tau_a - \tau_w) - \rho_i h g \nabla H_d + \nabla \cdot \sigma = 0$$

↑
rheology
term

Tremblay and Mysak 1997

The granular sea ice model: the rheology term



$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{bmatrix}$$

$$p = -\left(\frac{\sigma_{11} + \sigma_{22}}{2}\right)$$

$$q = \sqrt{\left(\frac{\sigma_{11} - \sigma_{22}}{2}\right)^2 + \sigma_{12}^2}$$

p and q are called the stress invariants

The granular sea ice model: the failure criterion

Failure criterion: defines the transition between the rigid phase and the plastic phase

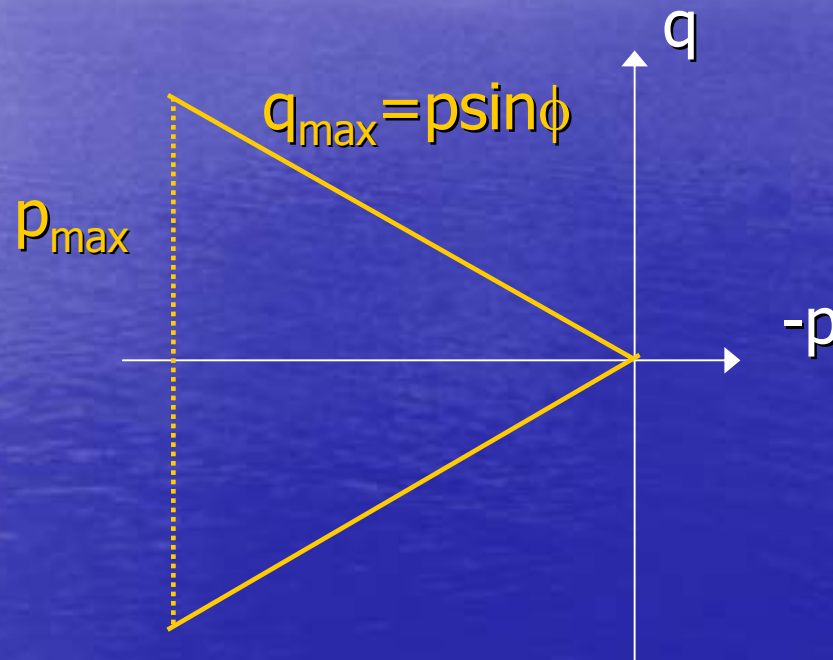
- failure in compression: $p_{\max} = p^* h e^{-C(1-A)}$ Hibler 1979

- failure in tension: free drift

- failure in shear: $\tau_s = -\sigma_s \tan \phi \Rightarrow q_{\max} = p \sin \phi$

– Mohr-Coulomb failure criterion

The granular sea ice model: the failure criterion



The failure criterion in stress invariants space

The granular sea ice model: the rheology term

To close the system of equations, we can relate the stress tensor to the strain rates

$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{bmatrix}$$

$$\sigma_{ij} = -p\delta_{ij} - \eta \dot{\varepsilon}_{kk} \delta_{ij} + 2\eta \dot{\varepsilon}_{ij}$$

$$\eta = \min \left(\frac{p \sin \phi}{\sqrt{\left(\dot{\varepsilon}_{11} - \dot{\varepsilon}_{22} \right)^2 + 4 \dot{\varepsilon}_{12}^2}}, \eta_{\max} \cos^2 \phi \right)$$

Tremblay and Mysak 1997

Numerical scheme:

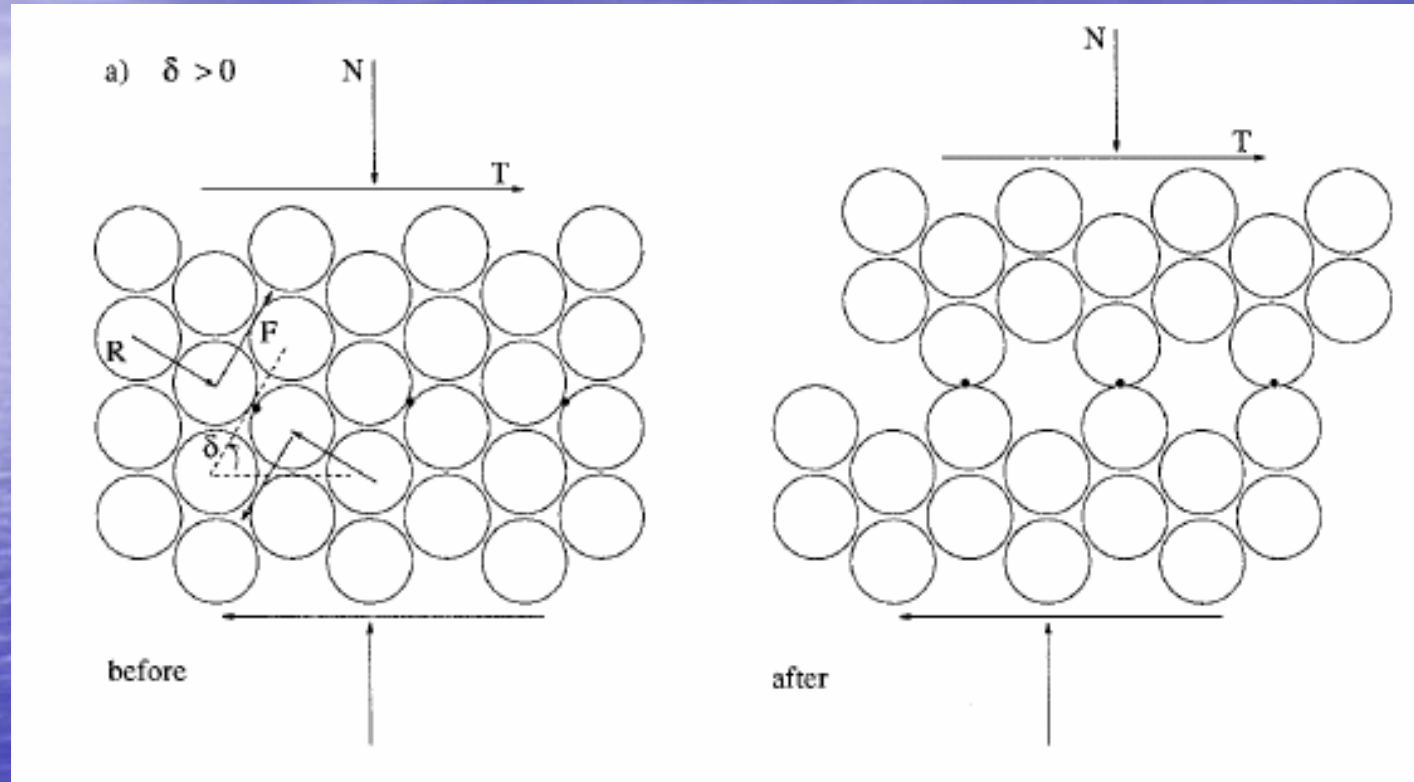
free drift u, v

do $k=1, \#$ iterations

- pressure calculation and correction of u, v (Flato and Hibler 1992)
- η calculation and correction to u, v

enddo

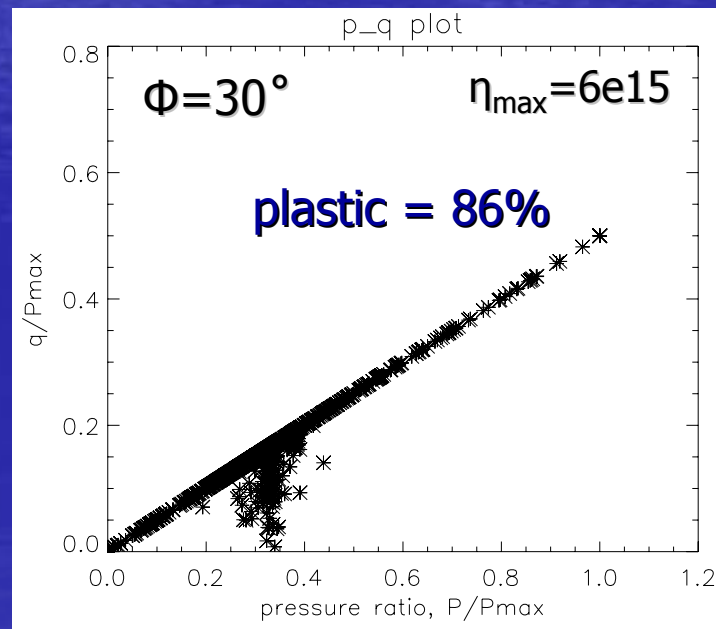
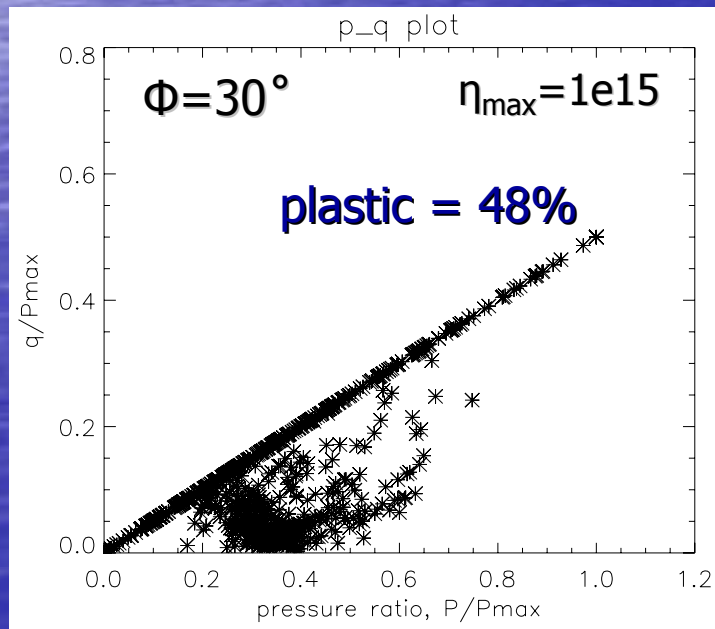
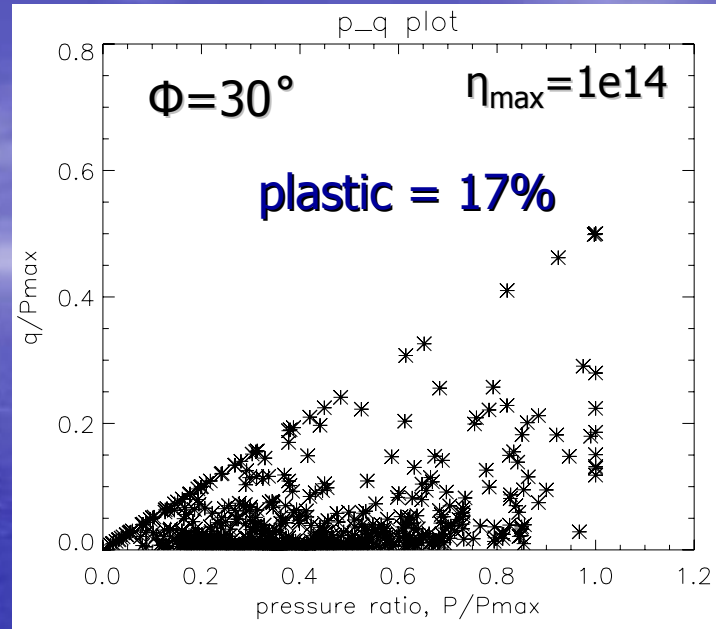
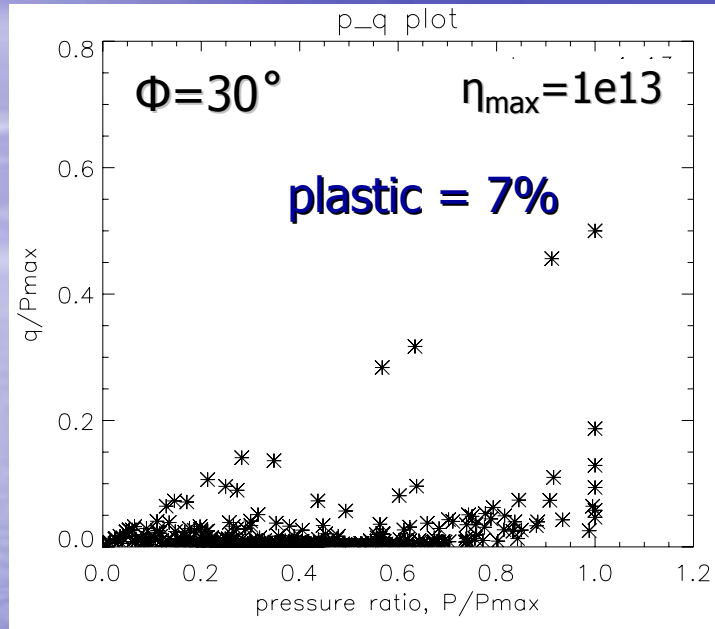
The granular sea ice model: the dilatancy effect



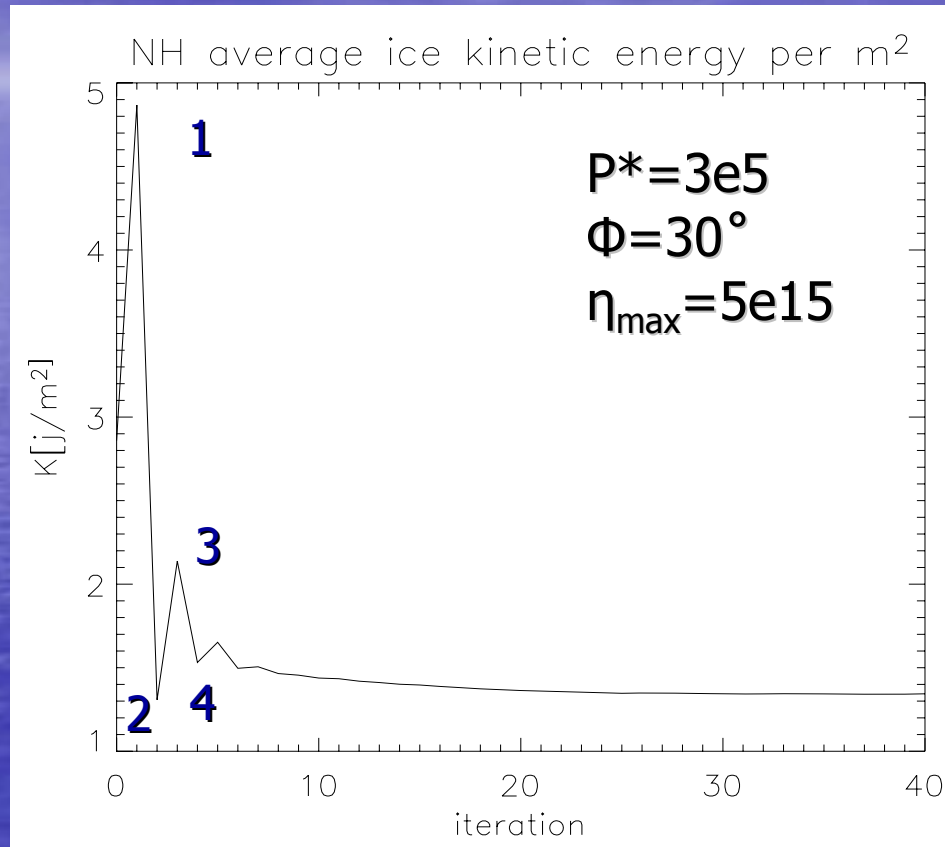
Research objectives

- To convert the granular sea ice model to spherical coordinates ✓ **done**
- To couple the granular model to the UVic model ✓ **done**
- Validate the coupled model (compare with Arctic observations)
- Propose and implement improvements to the granular sea ice model
- Improve the numerical scheme of the granular sea ice model

Preliminary results: η_{\max} and the plastic phase

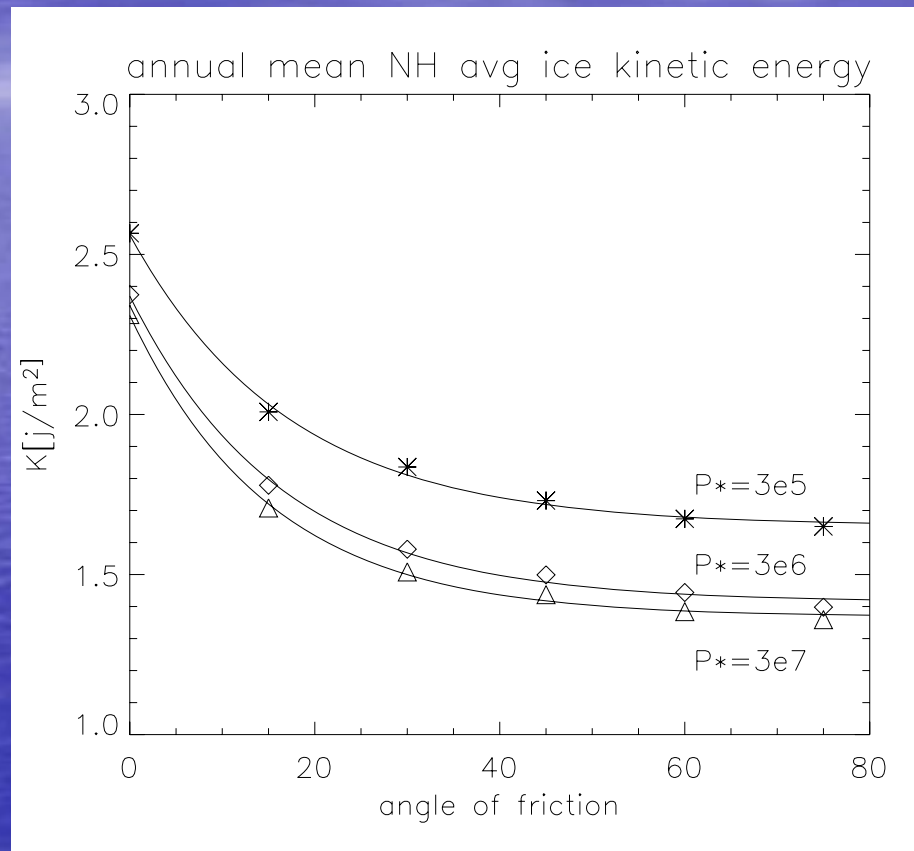


Preliminary results: how many iterations are needed?



Preliminary results:

Annual mean NH average K as a function of P^* and the angle of friction



Summary

- The rigid and the plastic phases of sea ice are well represented by the model
- We should increase the number of iterations to allow the average kinetic energy to converge
- The annual mean average kinetic energy decreases as the ice strength and the angle of friction increase