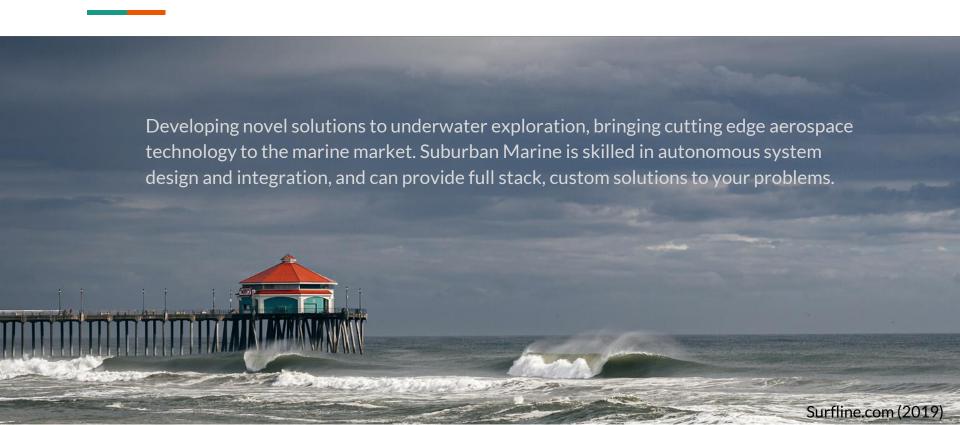


Overview



Customers















Services

Vehicle
Hardware standardization
Fault tolerance

Pixhawk, Ardupilot

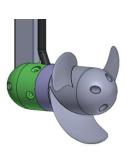


Power System

Battery management systems

Motor & thruster design

Motor controllers



Tembedded

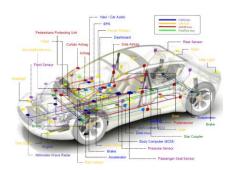
Networked autonomous systems

x86, ARM, PowerPC

Hard real-time control, data logging

4 Communication
Protocol translation
CAN bus
ROS

BLE, WiFi, LoRa



Products



6kW Field-Oriented Control ESC with CAN bus connectivity and exceptional thermal performance



Hadou-CAN

USB to CAN adapter for developing, debugging, and communicating with CAN based systems from your computer.



SM-1240

30A industrial quality motor control for small ROVs



UniCon

Build your own modular underwater connector for rapid integration and flexible assemblies.



Thank you.

