

Toy Model

Vortex Chain + Oscillations + Ekman Pumping

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Perturbed Hamiltonian Systems

➤ 2DOF

➤ 3DOF



2D steady + time

2D steady + 3rd

KAM Tori=Barriers

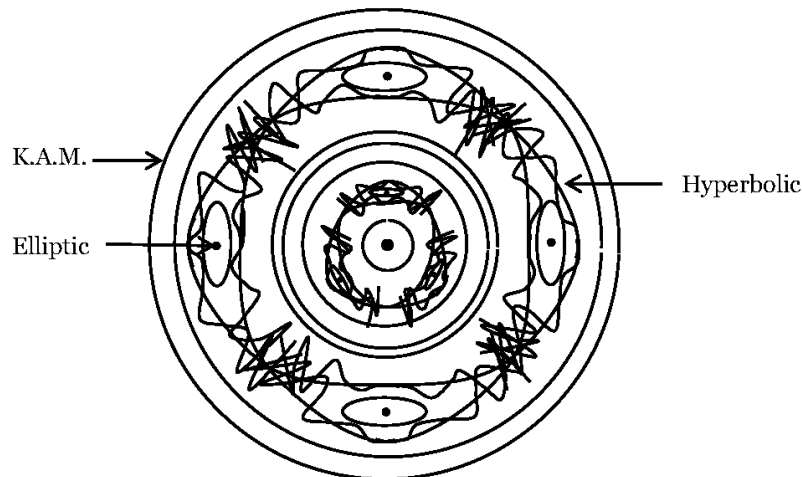
Chaos & Regular zones

Action-Angle

KAM Tori \neq Barriers

Arnold Diffusion

2Actions-2Angles



Toy Models

➤ 2DOF

➤ 3DOF



Can Model

Vortex Model

$$\dot{I} = \varepsilon F_1(I, \phi_1, \phi_2, t)$$

$$\dot{I}_1 = \varepsilon F_1(I, \phi_1, \phi_2, t)$$

$$\dot{\phi}_1 = \Omega_1(I) + \varepsilon F_2(I, \phi_1, \phi_2, t)$$

$$\dot{I}_2 = \varepsilon F_2(I, \phi_1, \phi_2, t)$$

$$\dot{\phi}_2 = \Omega_1(I) + \varepsilon F_3(I, \phi_1, \phi_2, t)$$

$$\dot{\phi} = \Omega(I) + \varepsilon F_3(I, \phi_1, \phi_2, t)$$

Action-Angle-Angle

1 Slow & 2 Fast Variables

Action-Action-Angle

2 Slow & 1 Fast Variables

Toy Models

➤ 2DOF

➤ 3DOF



Can Model

$$\dot{I} = \varepsilon F_1(I, \phi_1, \phi_2, t)$$

$$\dot{\phi}_1 = \Omega_1(I) + \varepsilon F_2(I, \phi_1, \phi_2, t)$$

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Action-Angle-Angle

2 Slow & 1 Fast Variables

Vortex Model

$$\dot{I}_1 = \varepsilon F_1(I, \phi_1, \phi_2, t)$$

$$\dot{I}_2 = \varepsilon F_2(I, \phi_1, \phi_2, t)$$

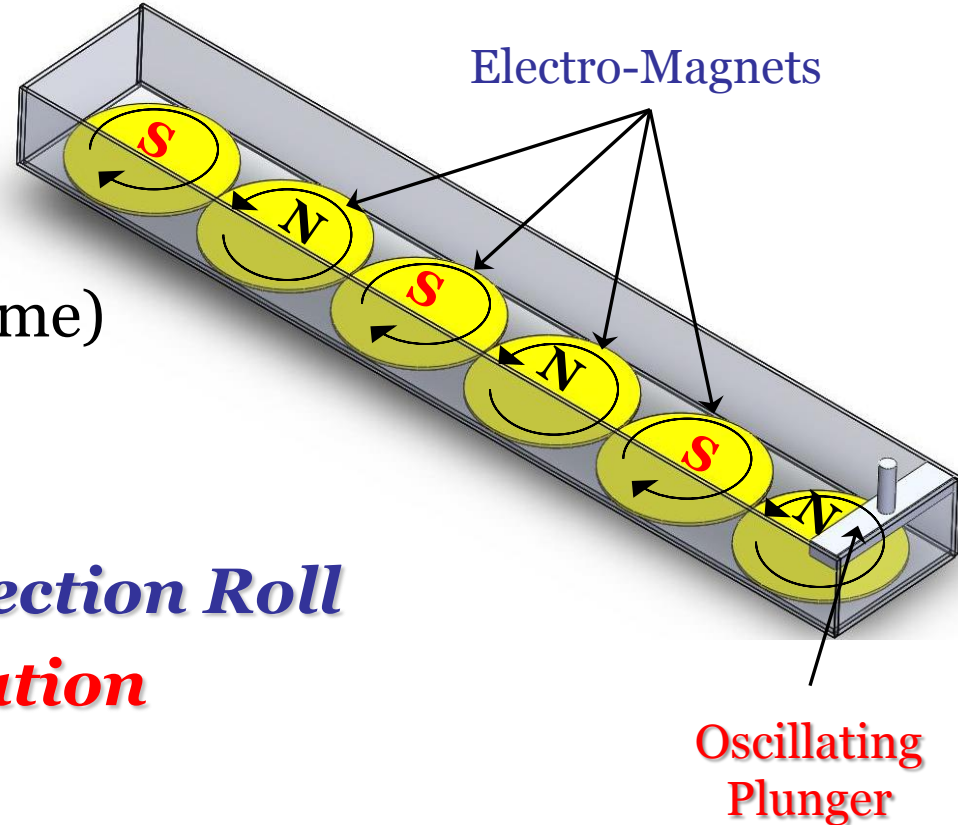
$$\dot{\phi} = \Omega(I) + \varepsilon F_3(I, \phi_1, \phi_2, t)$$

Action-Action-Angle

1 Slow & 2 Fast Variables

Physical Model & Assumptions

- Newtonian Incompressible Fluid
 - Slightly 3-D Open Flow
(Thin Electrolyte Layer)
 - No Waves are Excited
(Excitation period \ll Viscous time)
 - M.H.D. Technique
 - **Rayleigh-Bénard Convection Roll**
 - **Time Dependent Oscillation**
 - **3-D Ekman Pumping**
- System Diagram



Velocity Field/Dynamical System

➤ Dynamics of an Advected Particle

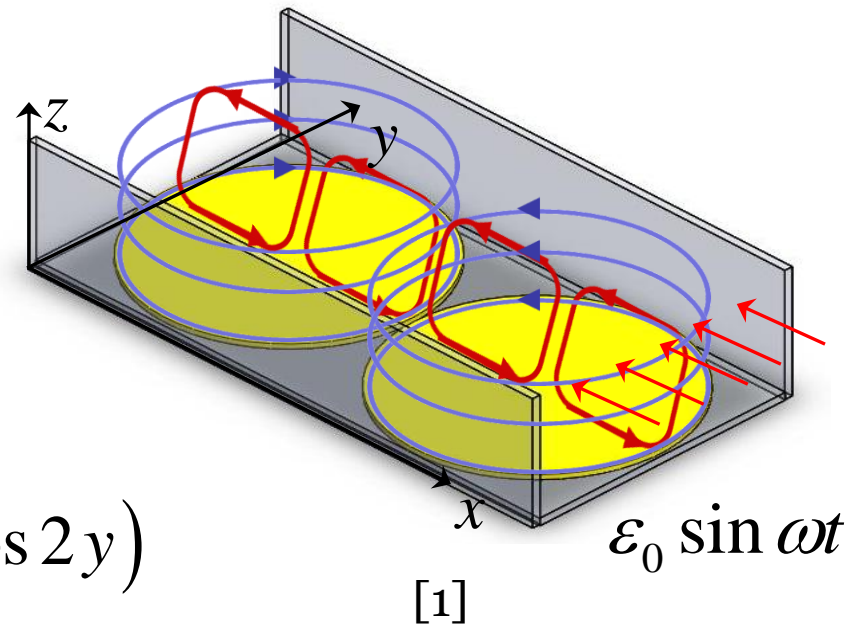
$$\dot{x} = \cos(x + \varepsilon_0 \sin \omega t) \sin y + \varepsilon_1 \sin(2x + 2\varepsilon_0 \sin \omega t) \sin z$$

$$\dot{y} = -\sin(x + \varepsilon_0 \sin \omega t) \cos y + \varepsilon_1 \sin 2y \sin z$$

$$\dot{z} = 2\varepsilon_1 \cos z (\cos(x + \varepsilon_0 \sin \omega t) + \cos 2y)$$

➤ Flow Structure

[1]



Unperturbed Case

➤ Action-Action-Angle

➤ Physical Space

$$\varepsilon_0 = 0 \quad \varepsilon_1 = 0$$

$$\dot{\psi} = 0 \quad \text{Action}$$

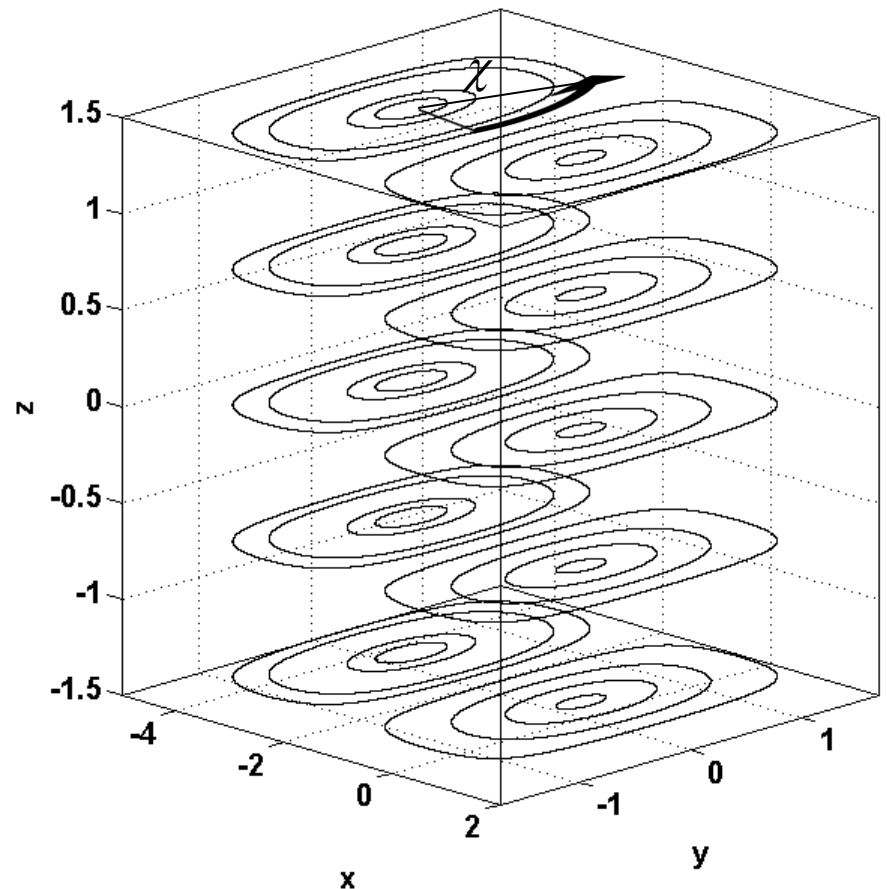
$$\dot{z} = 0 \quad \text{Action}$$

$$\dot{\chi} = \Omega(\psi) \quad \text{Angle}$$

$$\psi = \cos x \cos y$$

$$T(\psi) = 4 \int_0^{x_{\max}} (\cos^2(x) - \psi^2)^{-1/2} dx$$

$$x_{\max} = \frac{1}{\cos \psi} \quad \Omega(\psi) = \frac{2\pi}{T(\psi)}$$

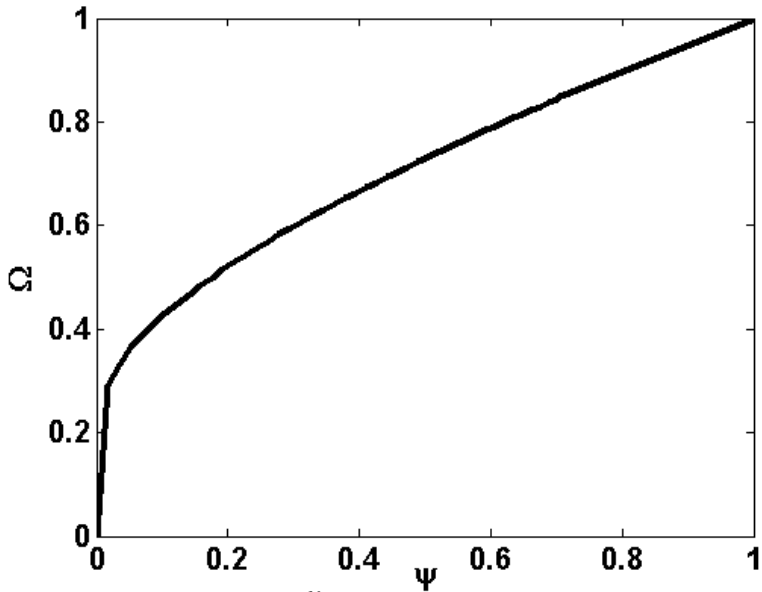


Unperturbed Case

➤ Action-Action-Angle

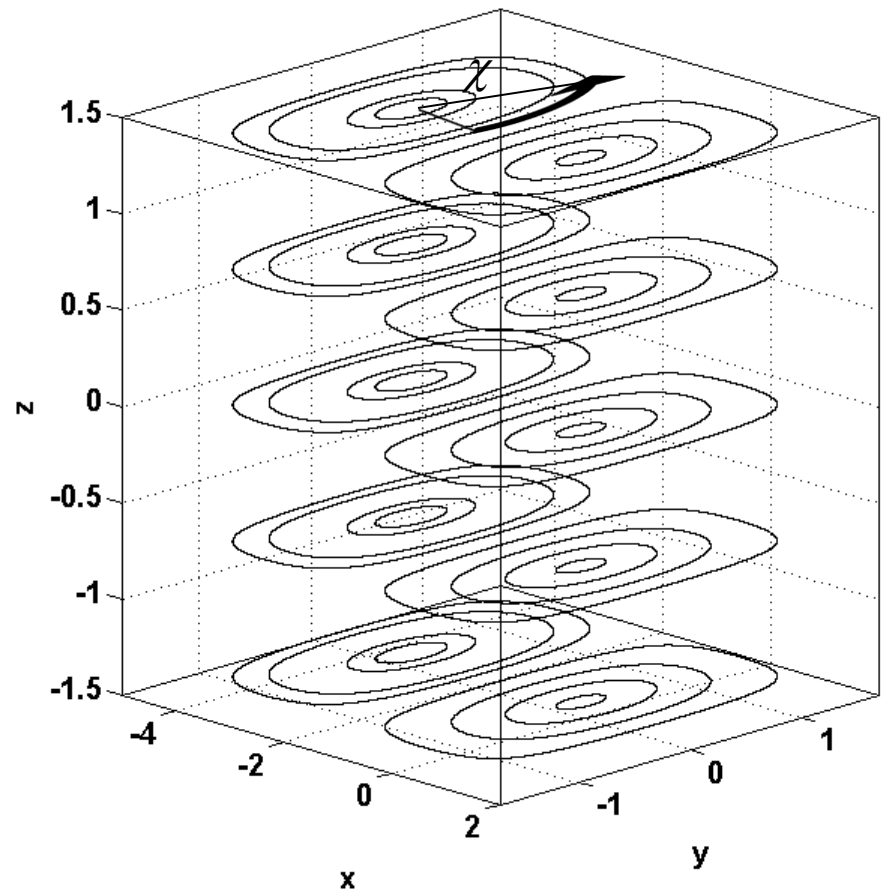
➤ Physical Space

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$$T(\psi) = 4 \int_0^{x_{\max}} (\cos^2(x) - \psi^2)^{-1/2} dx$$

$$x_{\max} = \frac{1}{\cos \psi} \quad \Omega(\psi) = \frac{2\pi}{T(\psi)}$$



Perturbed Case

➤ Perturbation of Action-Action-Angle

$$\omega = O(\Omega) = O(1) \quad \varepsilon_0 / \varepsilon_1 = O(1)$$

$$\dot{\psi} = -\frac{1}{2} \varepsilon_0 \sin(\omega t) G_0(\psi, \chi) - 2\varepsilon_1 \sin z\psi G_1(\psi, \chi)$$

$$\dot{z} = 2\varepsilon_1 \cos zH(\psi, \chi)$$

$$\dot{\chi} = \Omega(\psi) + \varepsilon_0 I_0(\psi, z, \chi) + \varepsilon_1 I_1(\psi, z, \chi)$$

$$G_0(\psi, \chi) = \sin 2y$$

(ψ, z) 2 Slow Variables

$$H(\psi, \chi) = \cos 2y + \cos 2y$$

+

χ 1 Fast Variable

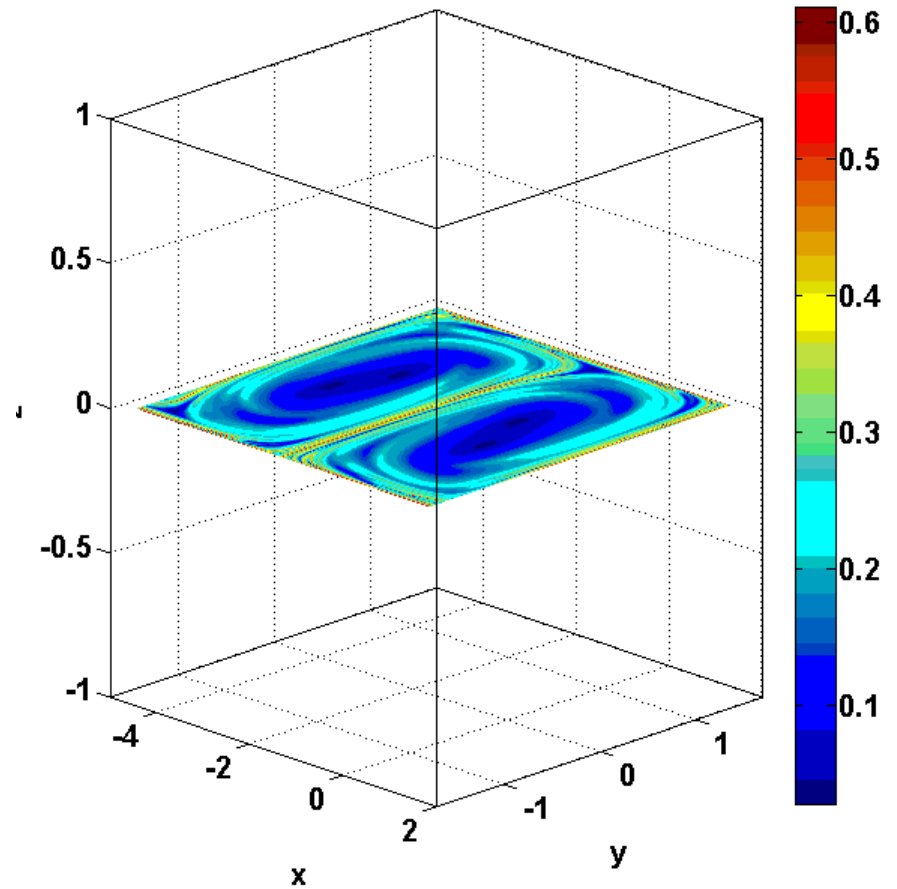
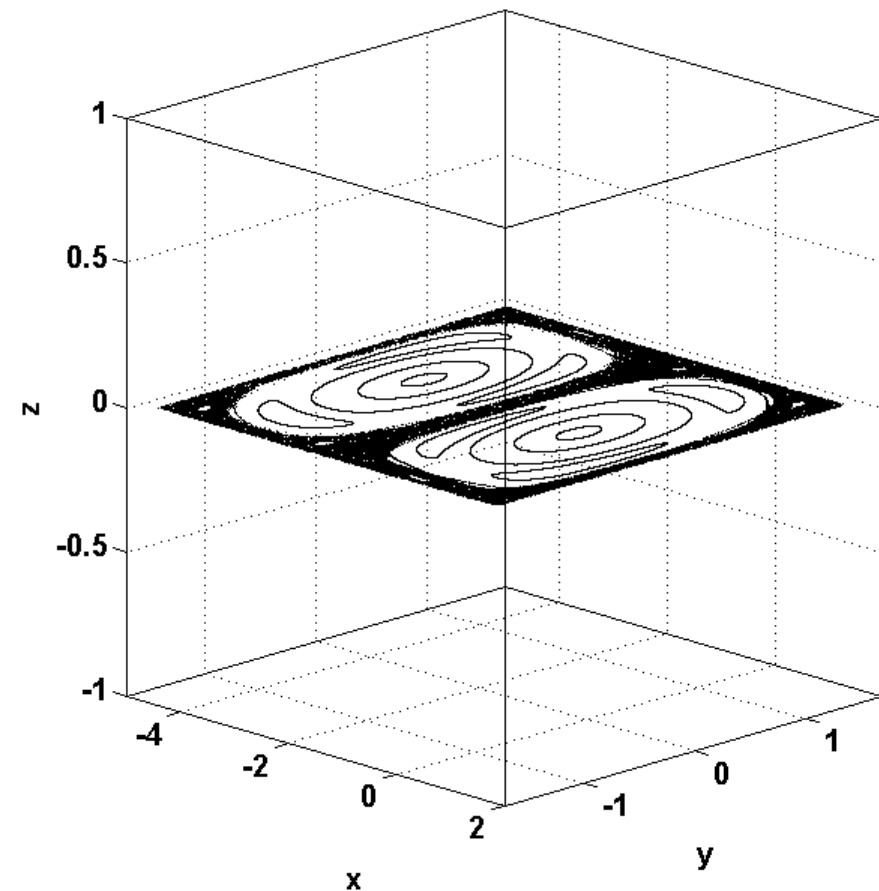
$$G_1(\psi, \chi) = \sin^2 x + \sin^2 y$$

Two Dimensional + Time Dependent Case

➤ Poincaré Section

$$\varepsilon_0 = 0.1 \quad \varepsilon_1 = 0 \quad \omega = 2.00 \quad t = 8\pi/\omega$$

➤ F.T.L.E.



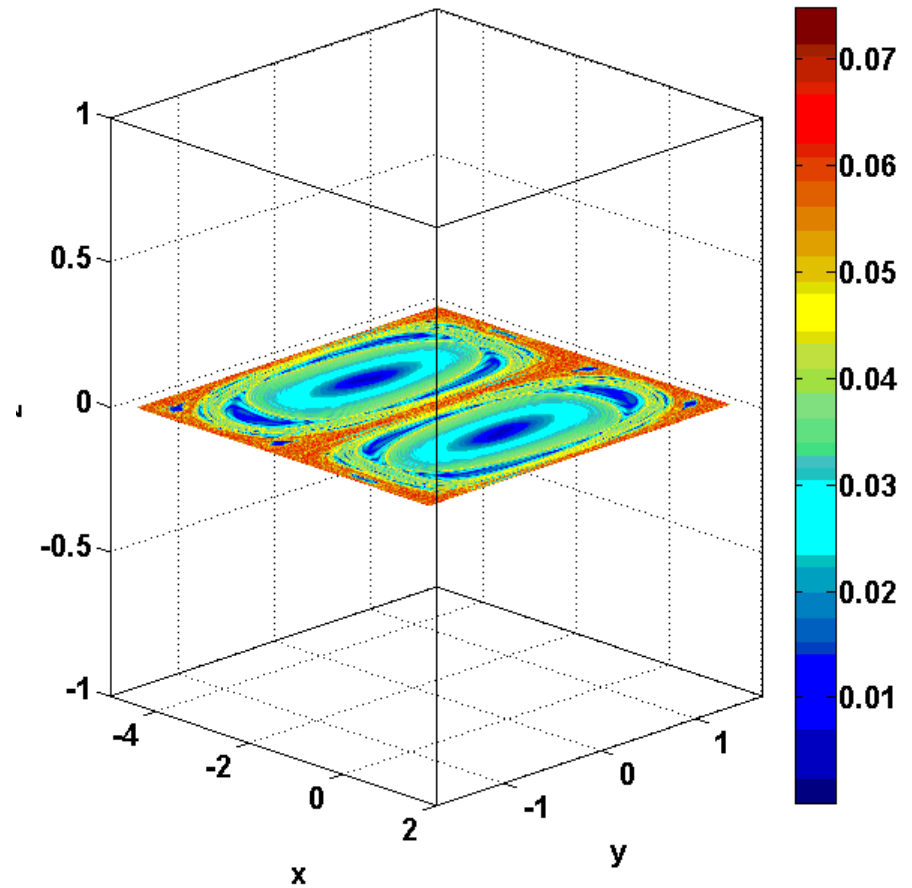
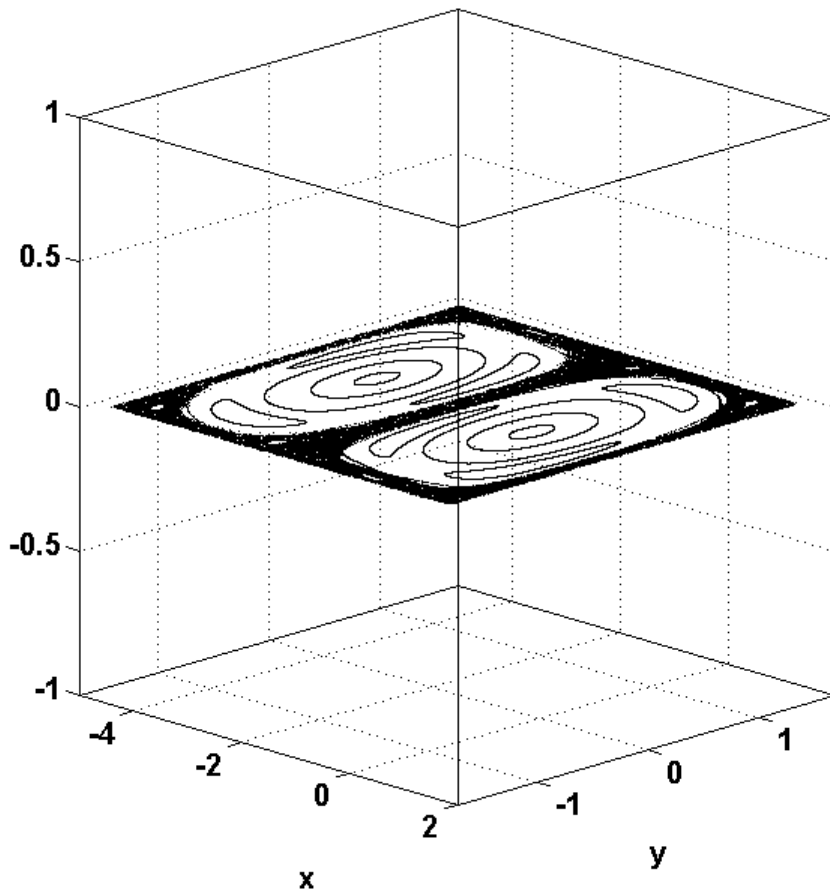
Two Dimensional + Time Dependent Case

➤ Poincaré Section

$$\varepsilon_0 = 0.1 \quad \varepsilon_1 = 0$$

➤ F.T.L.E.

$$\omega = 2.00 \quad t = 80\pi / \omega$$



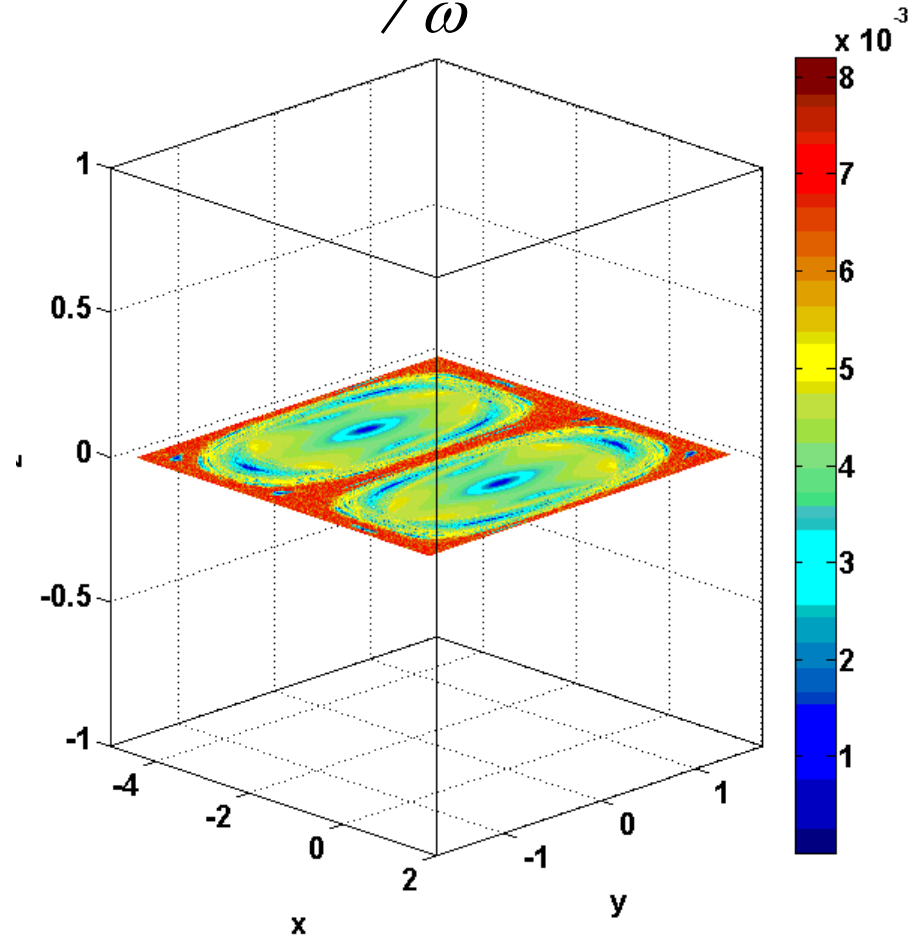
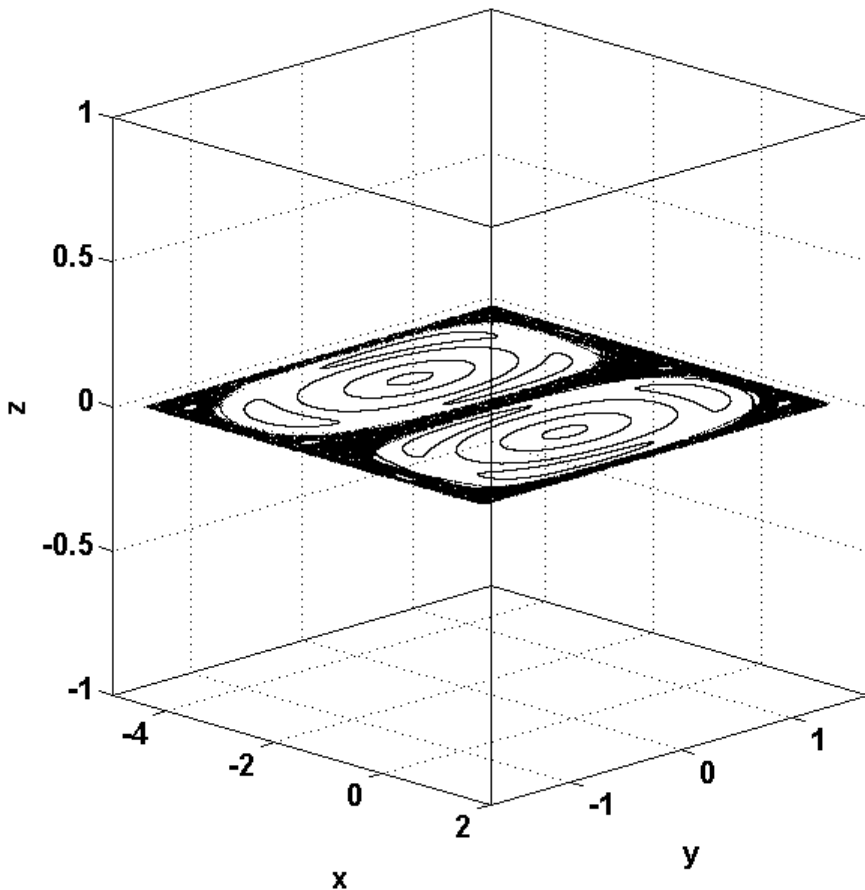
Two Dimensional +Time Dependent Case

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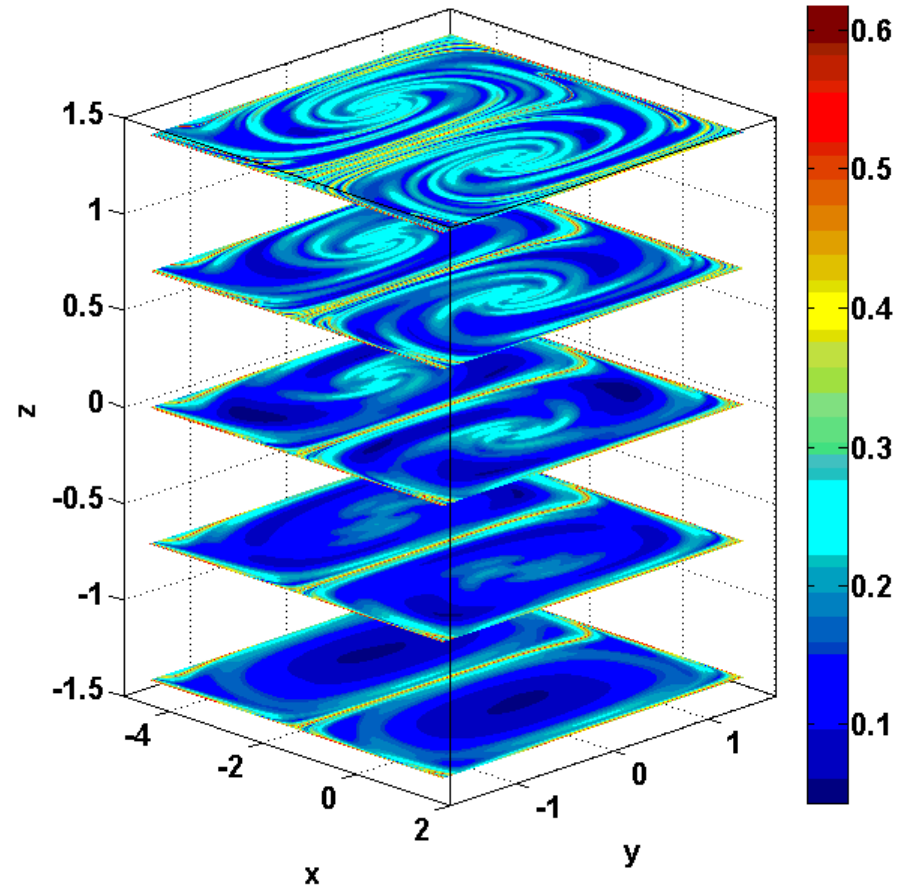
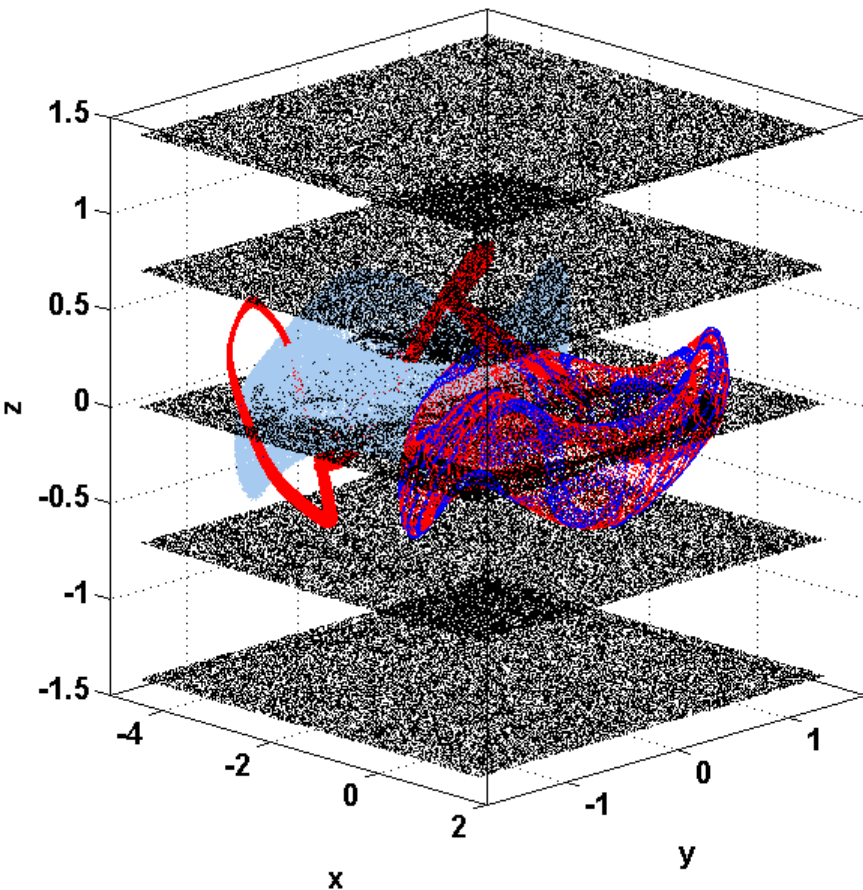


Three Dimensional +Time Dependent Case

➤ Poincaré Sections

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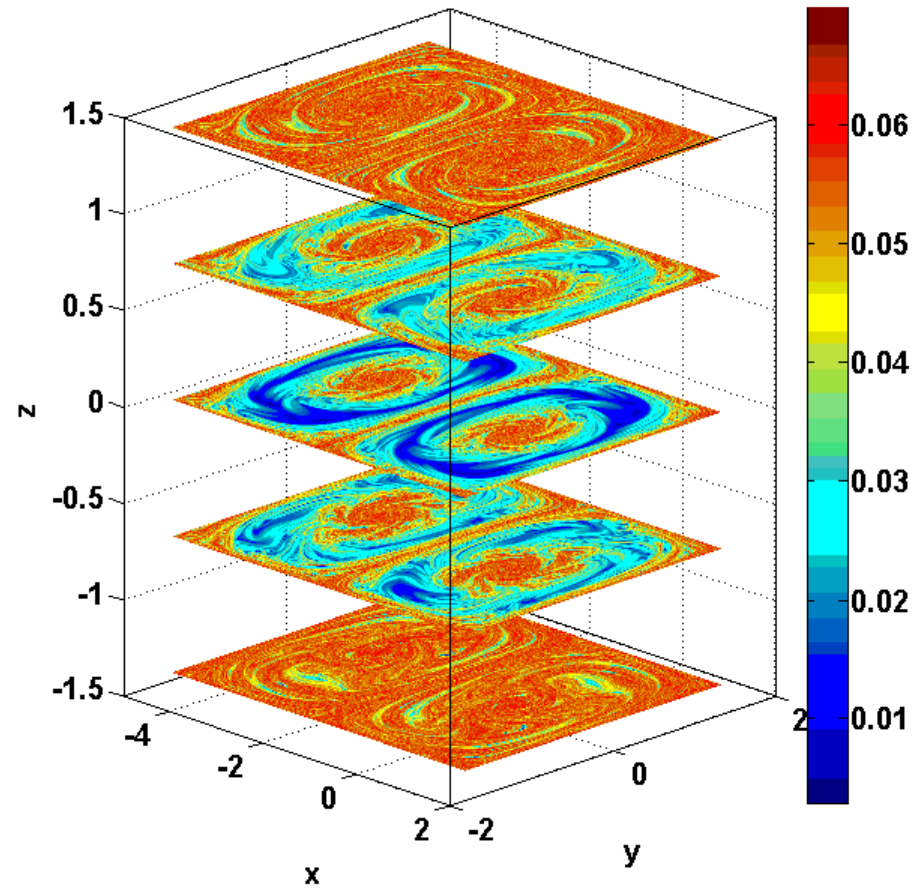
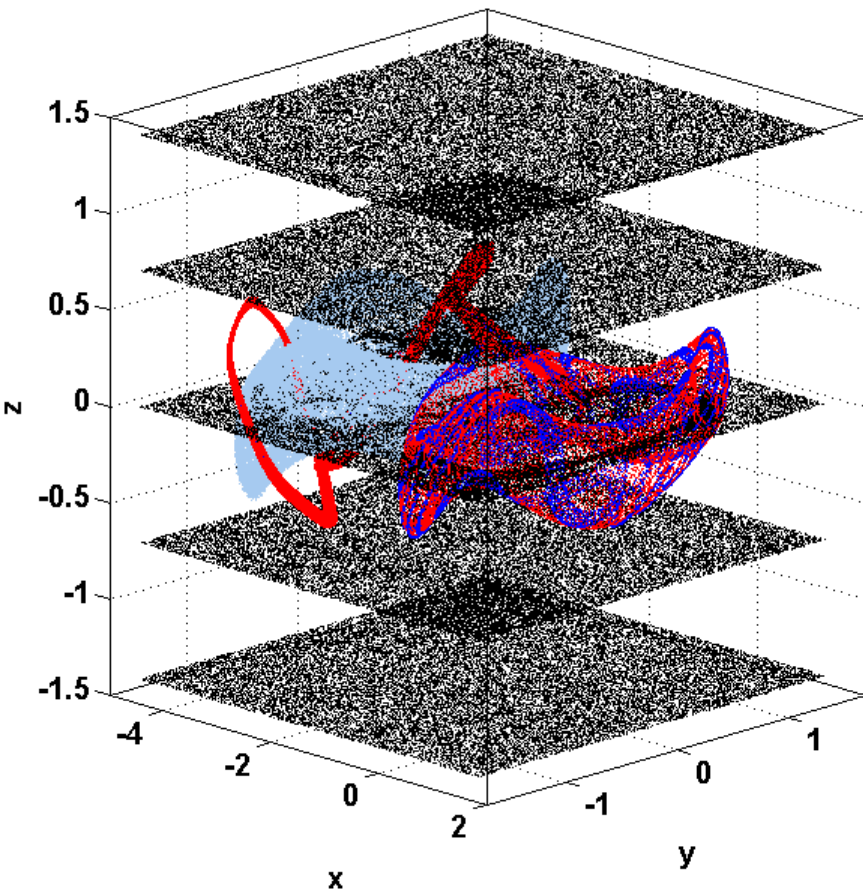


Three Dimensional +Time Dependent Case

➤ Poincaré Sections

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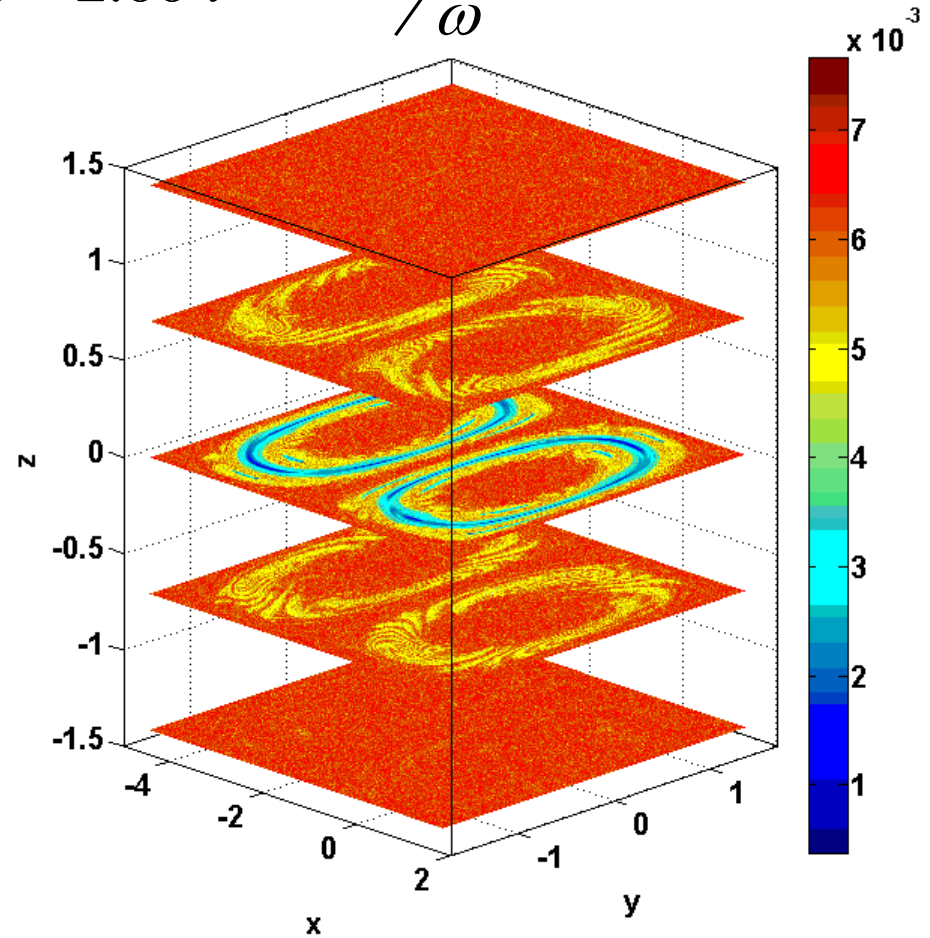
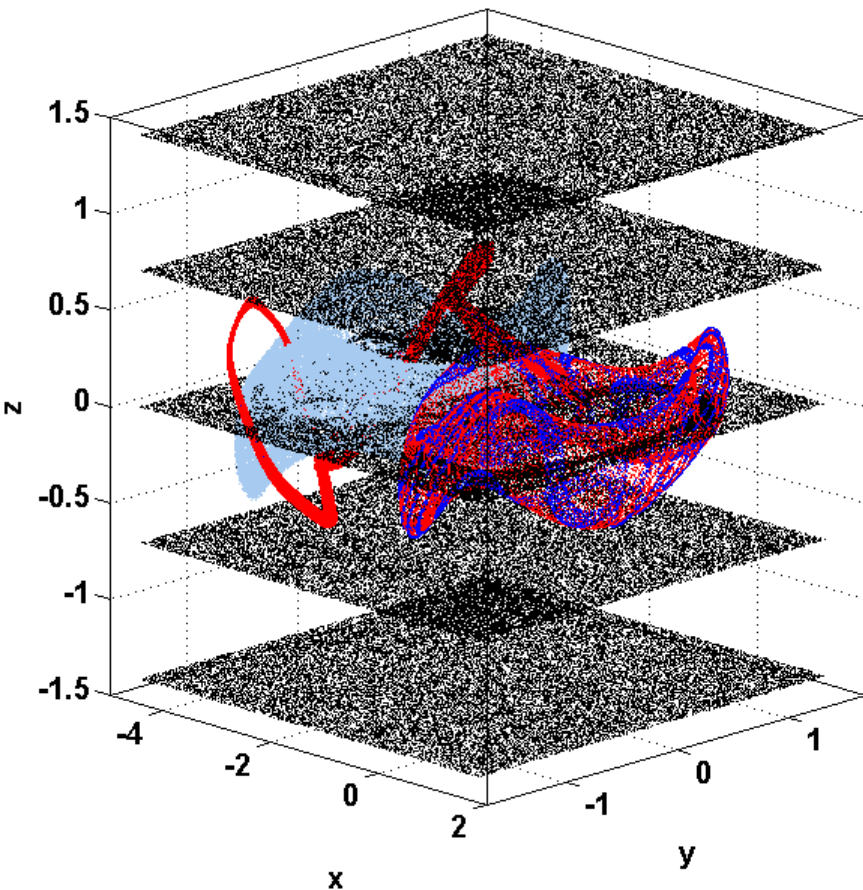


Three Dimensional +Time Dependent Case

➤ Poincaré Sections

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Next Steps

- Resonances
- Capture into Resonance
- Scattering
- Key periodic Orbits

